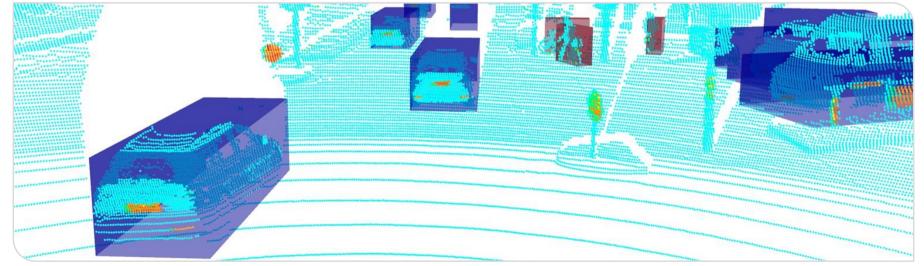




# **Benefits and Challenges of Next Generation Datasets**

Dr. Carlos Fernandez (Karlsruhe Institute of Technology)



# Introduction







# Introduction







### **Current State of Vehicle Datasets**





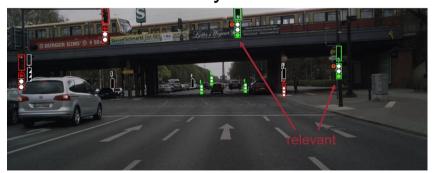
Cityscapes



Cityscapes 3D



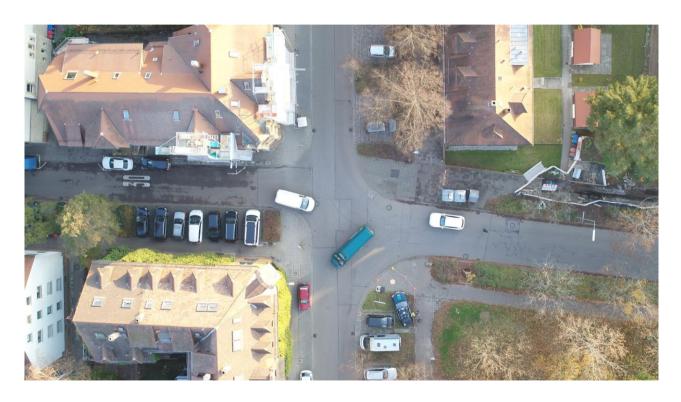
Euro City Person



Drive U

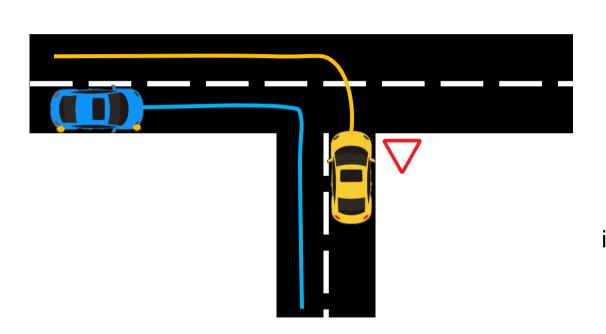
# **Current State of Drone Datasets**

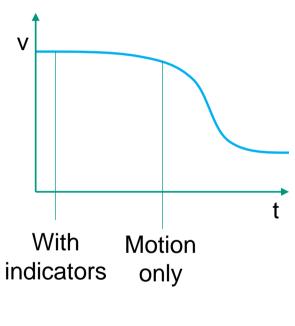




### **Current State of Drone Datasets**







### **Benefits of Next Generation Datasets**





- Object detection
- Tracking
- Trajectory filtering
- Speed estimation
- Orientation

#### **Benefits of Next Generation Datasets**



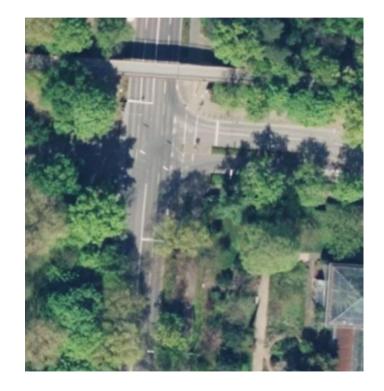


- Object height
- Traffic light state
- Car indicators
- Pedestrian head pose

# **Challenges of Next Generation Datasets**

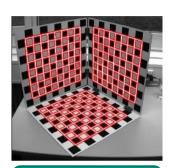






# **Challenges of Next Generation Datasets**





Camera Calibration





Vehicle-Drone Synchronization



Vehicle Localization

Drone Image Stabilization



**Drone Image** Georeference

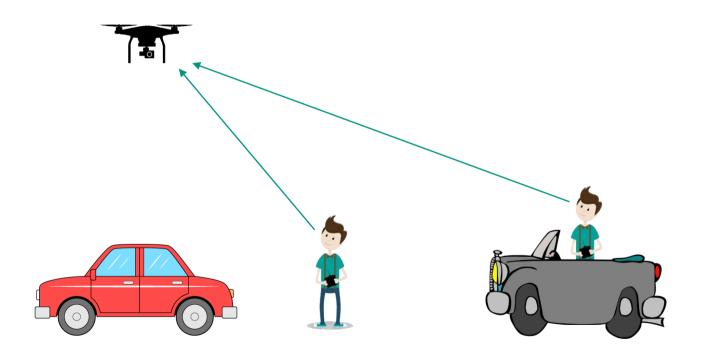


**Drone Grid** Management



## **Even Further Generation Datasets**





### Conclusions



- Current datasets are focused on specific tasks (Perception & Behavior).
- It would be good to have more detailed labels in the future datasets.
- Decision making datasets are missing features that influence behavior.
- Both worlds can meet each other and boost autonomous driving in the future.
- Technical and administrative challenges need to be addressed.



# Thanks for your attention